

PACE Applications to Case II Waters:

Lessons Learned from a Turbid, Pacific Coast Estuary

Steven Ackleson & Wesley Moses

Naval Research Laboratory, DC.



Environmental Overview

Shallow Embayments:

Wind mixing

High C_{SPM}

Low C_{CHL}

High a_{CDOM} , a_{SPM}

Wetlands Sources
of CDOM and POC

Sacramento River:

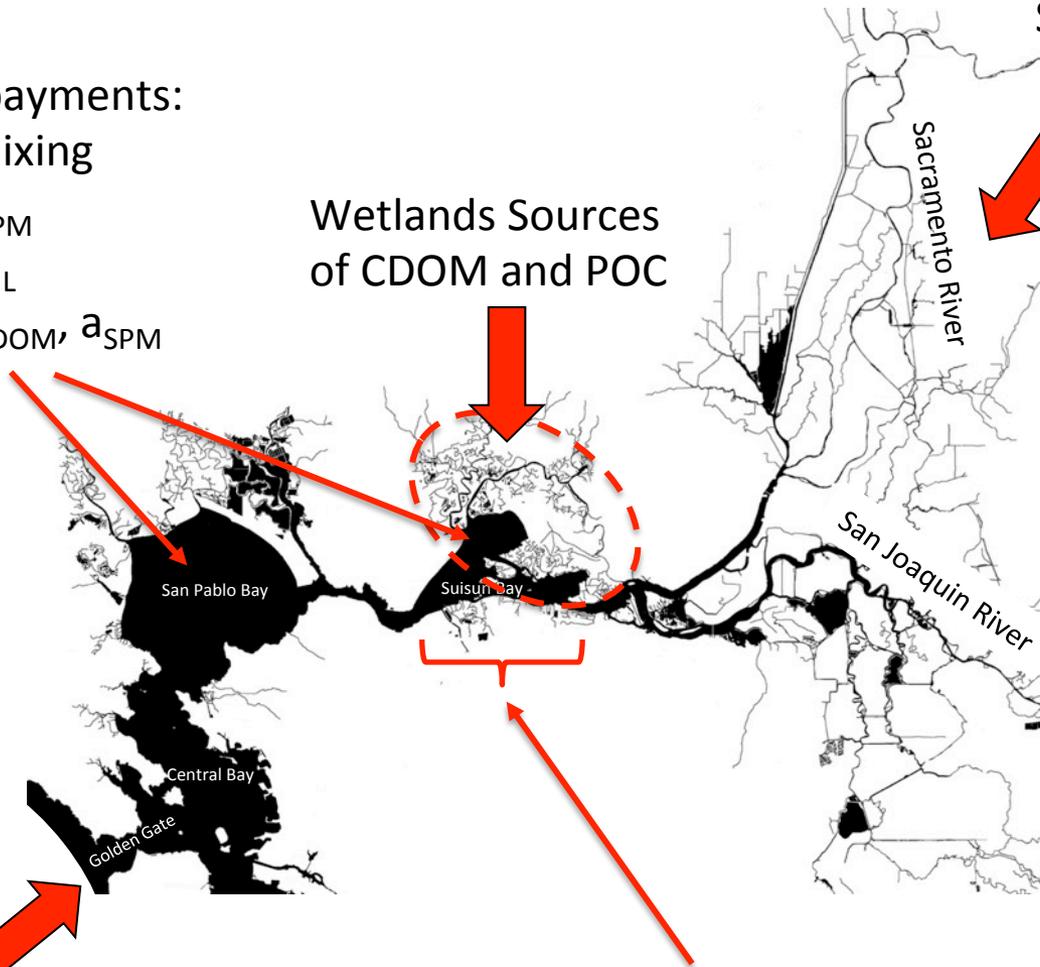
Low Salinity

Low C_{SPM}

Moderate C_{CHL}

Moderate a_{CDOM}

Low a_{SPM}



Coastal Water:

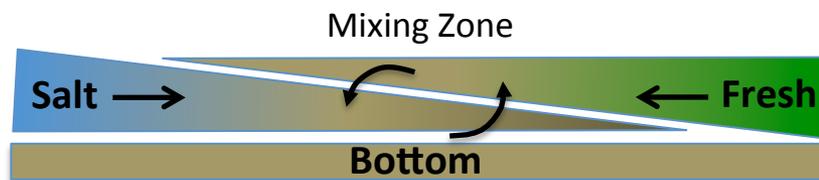
High Salinity

Low C_{SPM}

Moderate C_{CHL}

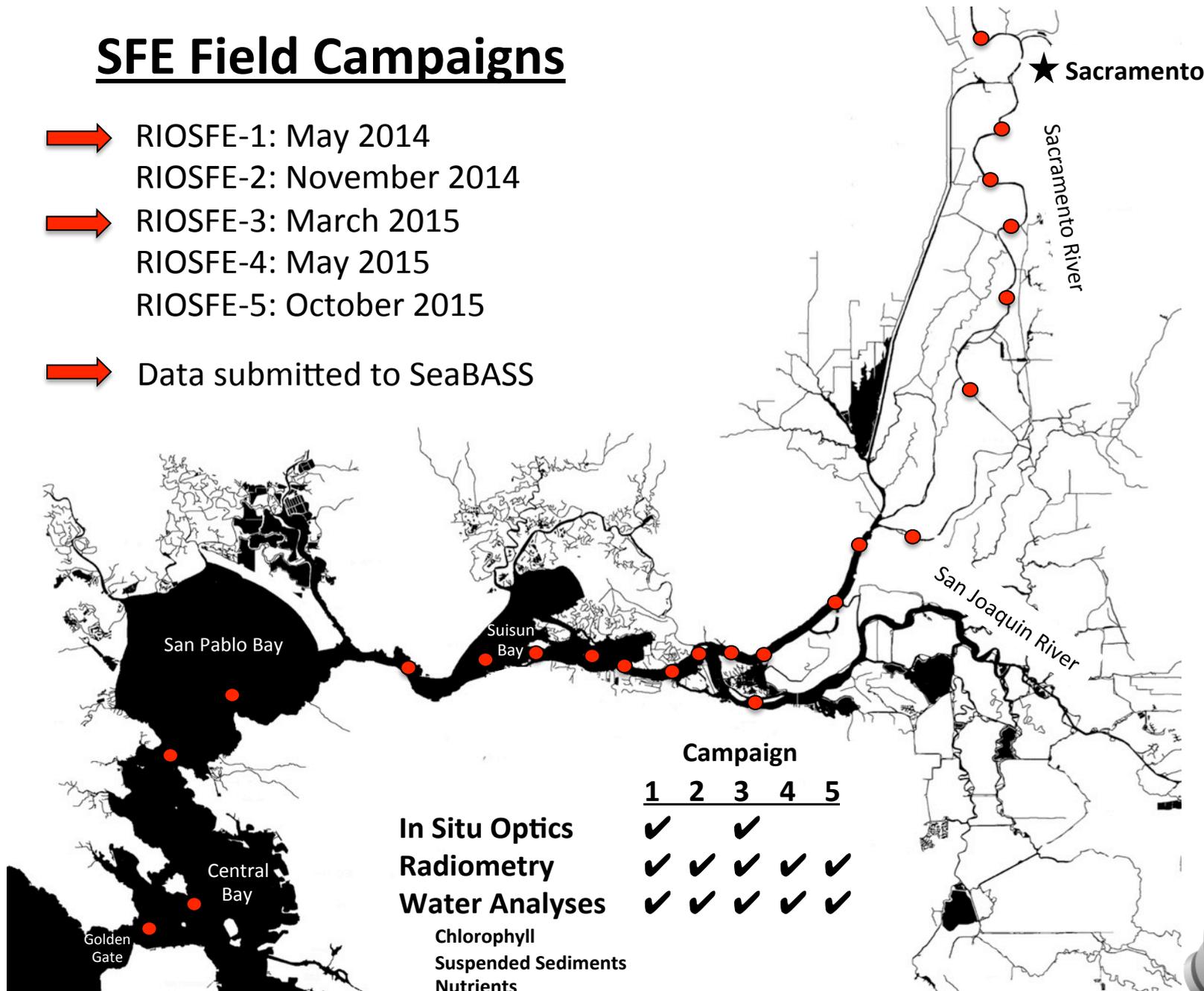
Low a_{CDOM} , a_{SPM}

Salt Wedge Dynamics

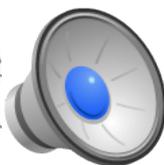


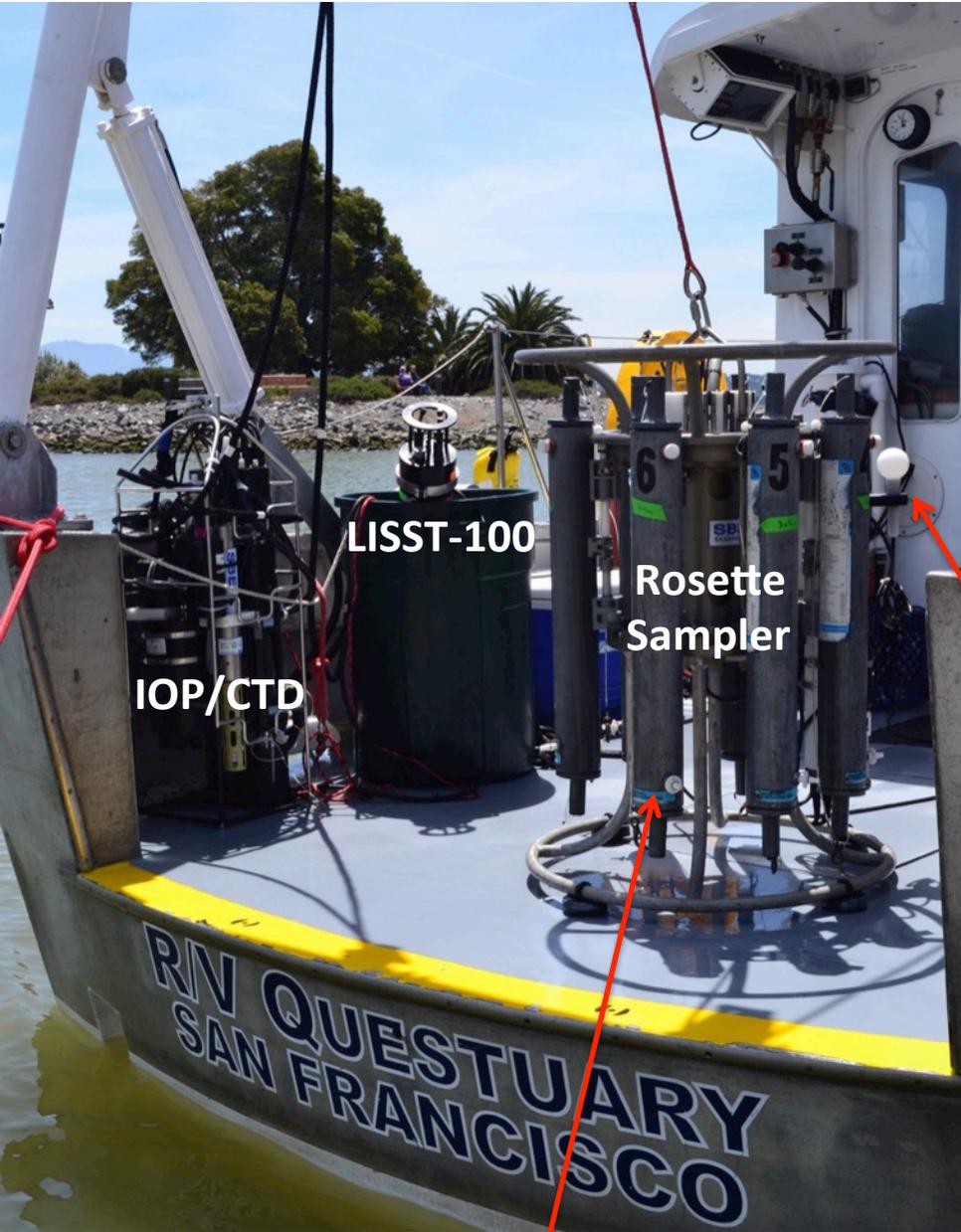
SFE Field Campaigns

- ➔ RIOSFE-1: May 2014
- RIOSFE-2: November 2014
- ➔ RIOSFE-3: March 2015
- RIOSFE-4: May 2015
- RIOSFE-5: October 2015
- ➔ Data submitted to SeaBASS



	Campaign				
	<u>1</u>	<u>2</u>	<u>3</u>	<u>4</u>	<u>5</u>
In Situ Optics	✓		✓		
Radiometry	✓	✓	✓	✓	✓
Water Analyses	✓	✓	✓	✓	✓
Chlorophyll					
Suspended Sediments					
Nutrients					





In Situ Optics

0.2 μm pre-filter attached to the ac-9



Spectral Backscatter Sensor (472, 526, and 654 nm)
Pre-Filters (ac-9 sensor)

PAR Sensor



Bouyancy Chamber

Spectral Absorption and Attenuation Sensors ac-9, ac-s

Conductivity, Temperature, and Depth Sensors (SBE 49)



LISST 100x

Above-Water Radiometry (ASD: 380 – 1100 nm)



Water samples analyzed for SPM, pigments, and nutrients

Data Quality: Beam Attenuation

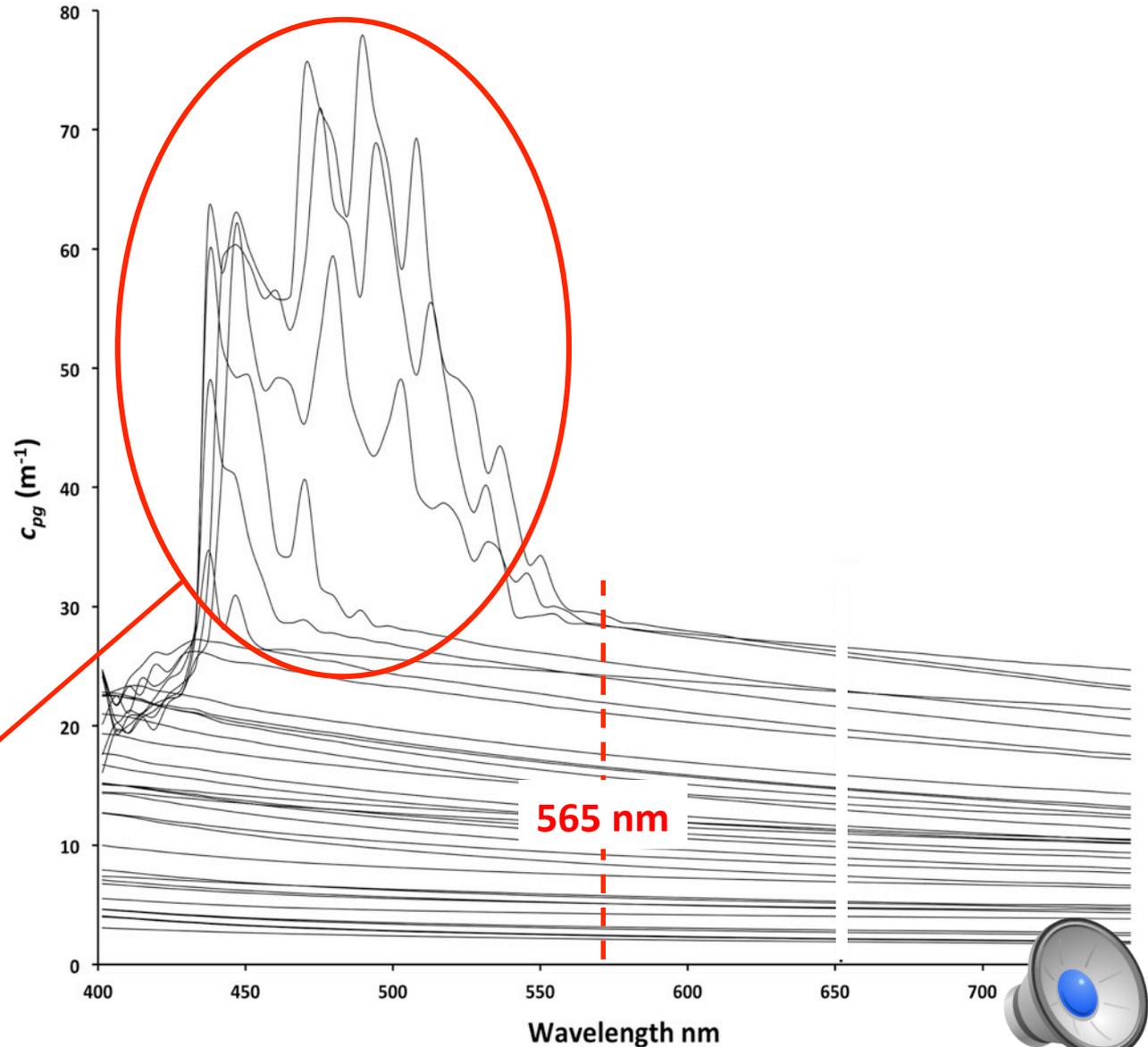


Secchi depth often less than 1 m!

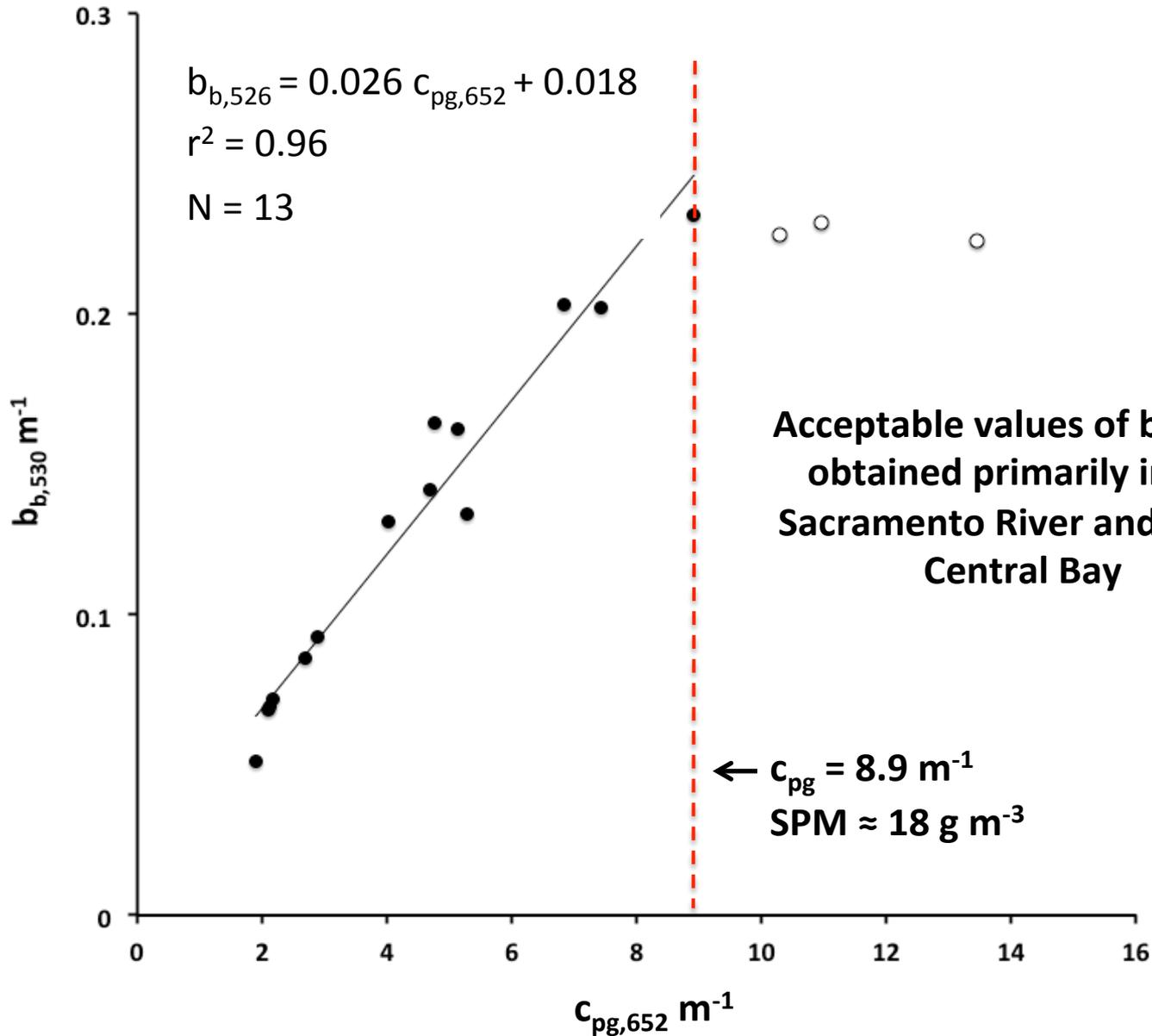
All data where

$$c_{pg,652} > 15.8 \text{ m}^{-1}$$

$$\text{SPM} > 33 \text{ g m}^{-3}$$



Data Quality: Backscatter

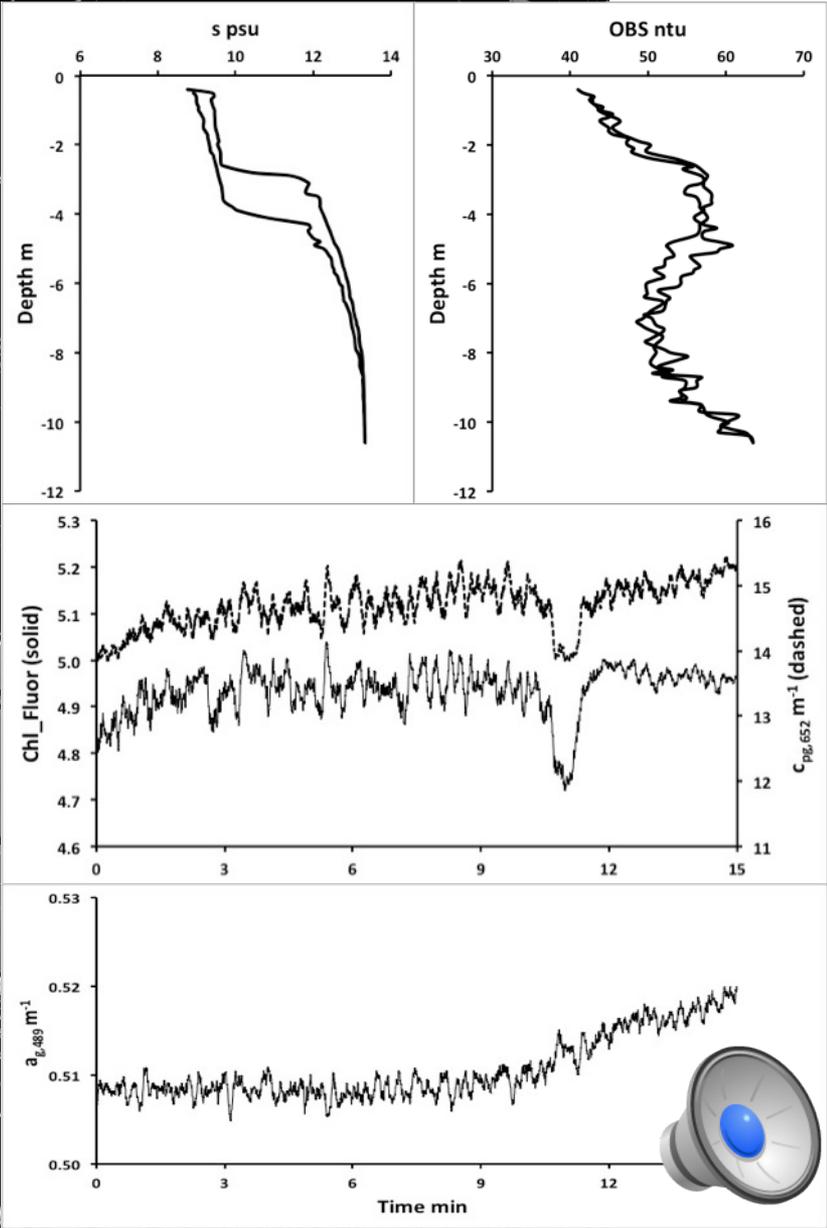


Impact of Correlation Scales

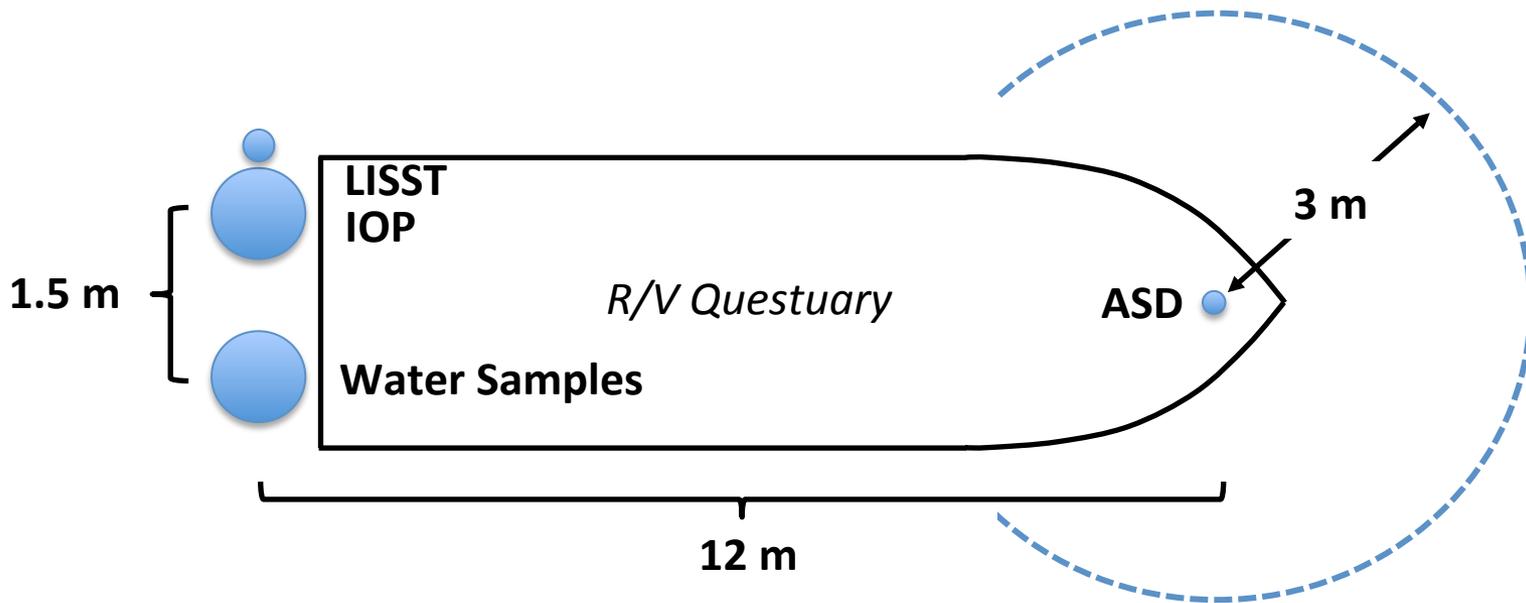
25 Mar 2015
Station: USGS 6
Lat: 38.065 N
Lon: 122.036 W
High Slack

Suisun Bay

Landsat-8, 21 Mar 2015



Impact of Correlation Scales



IOP Sensor Package



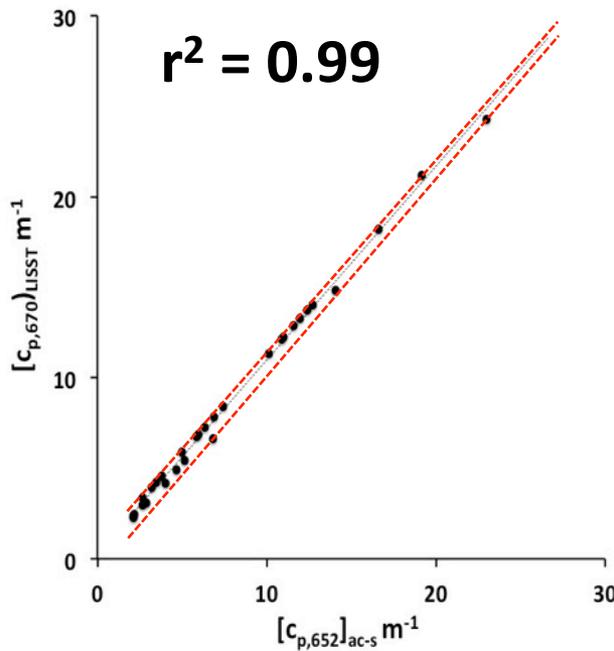
Water Sampler



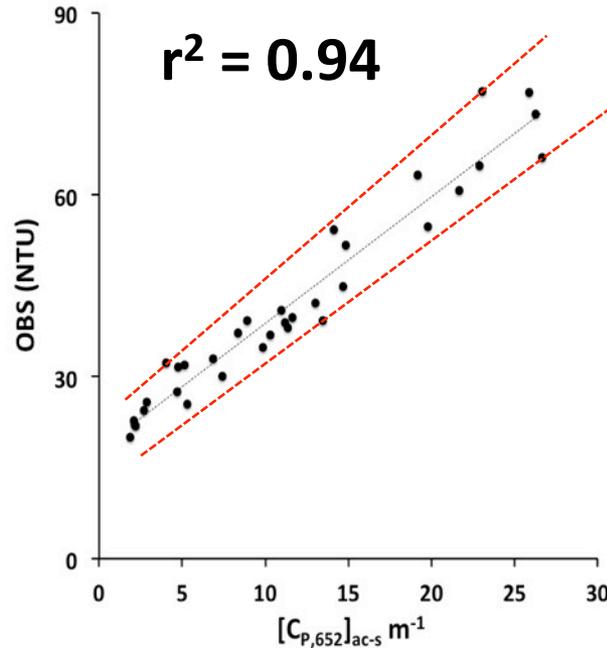
Impact of Correlation Scales: Sensor Spatial Offset

USGS 6, 25 March 2015, Suisun Bay

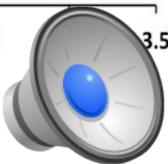
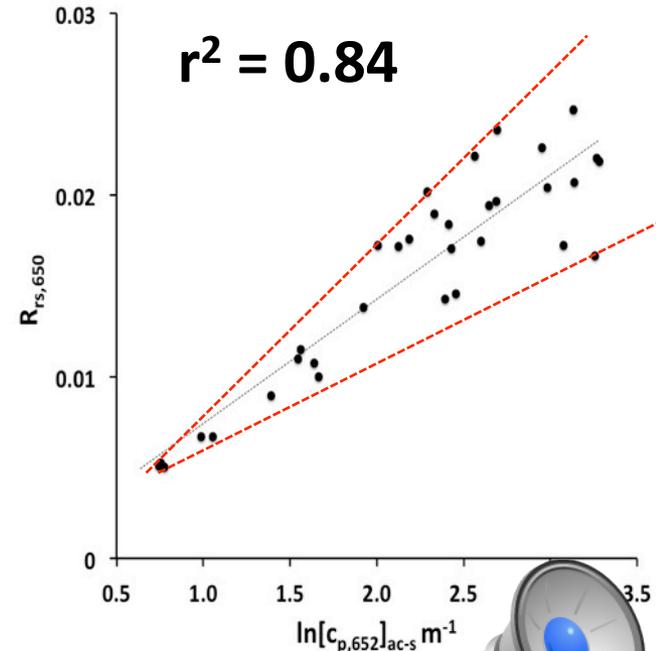
Two in situ sensors on
the same platform;
Offset ≈ 0.25 m



Two in situ sensors on
different platforms;
Offset ≈ 1.5 m

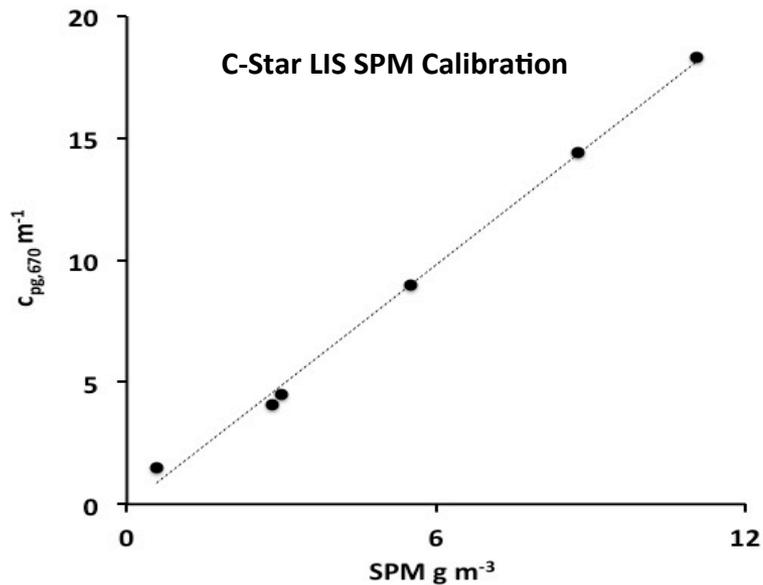
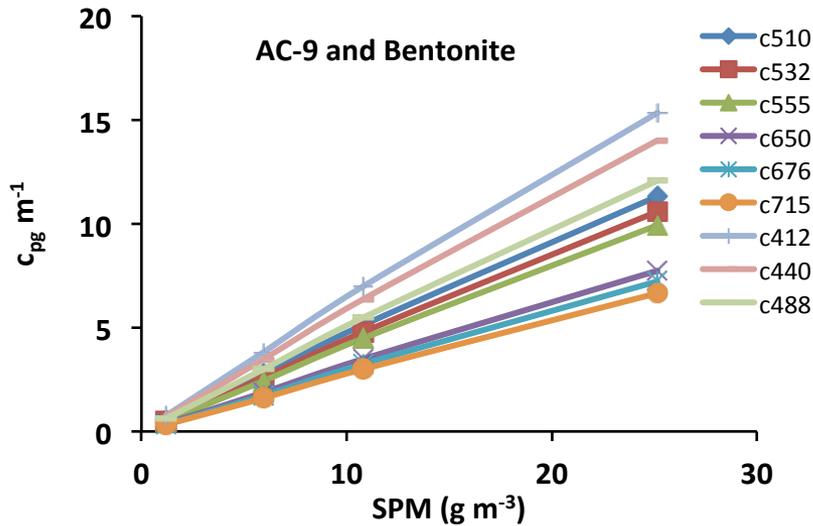


In situ sensor
compared with above-
water radiometry;
Offset $\approx 10\text{-}15$ m

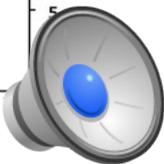
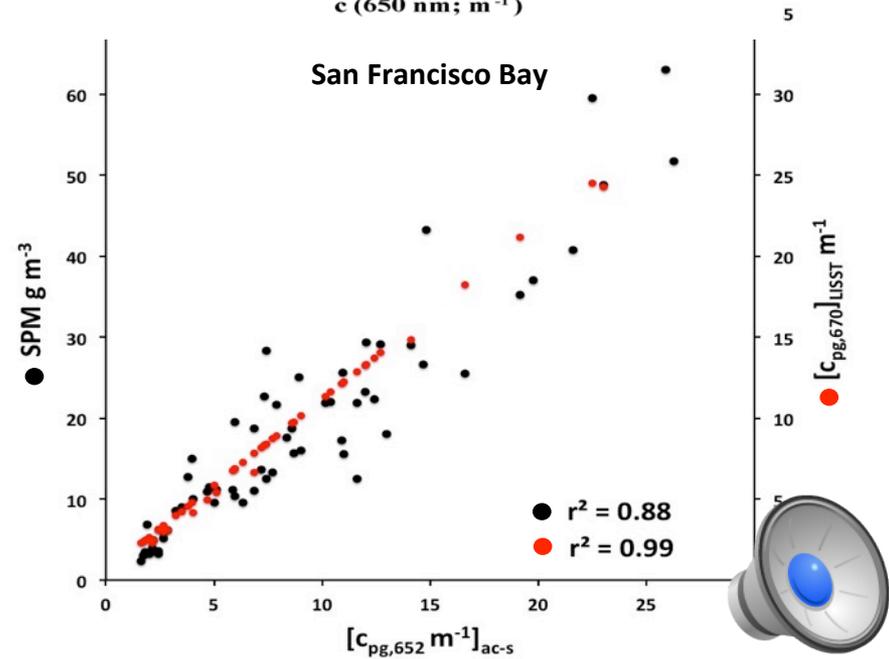
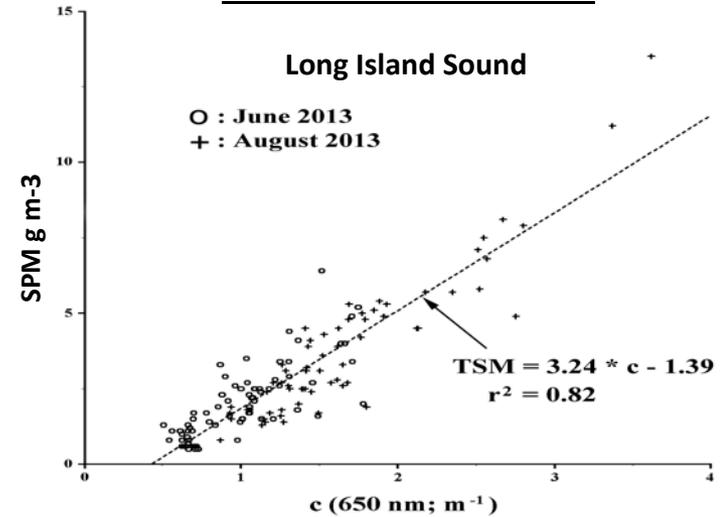


Impact of Correlation Scales: Water Sampling

Laboratory Calibrations



Field Observations



Lessons Learned



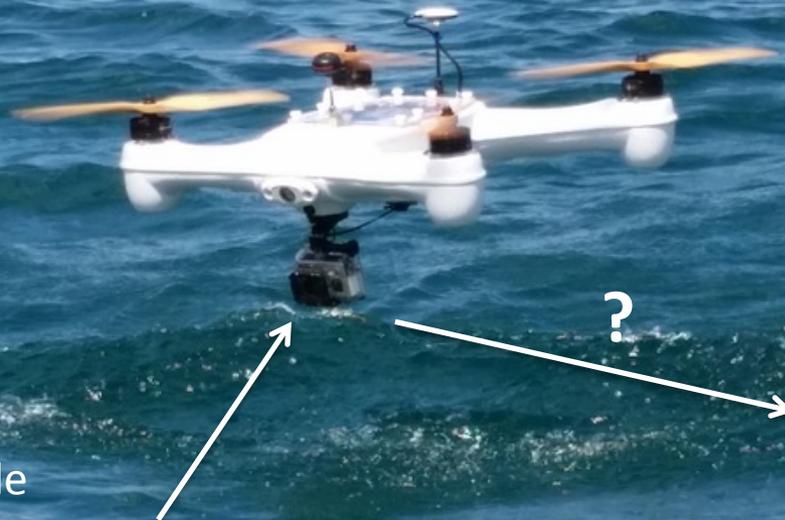
Moving Forward

We need to be able to measure water color in high spatial resolution at and around the locations where and when in situ observations and water samples are being collected.



Completely waterproof
Take-off and land on water
1.5 kg payload
15-30 minute flight time
GPS Navigation
Can operate in "follow" mode

GoPro



Headwall
Nanno-Hyperspec



Constituent-Based IOP Model: SFE-O

$$P = C \cdot P' \cdot F$$

	<u>SPM</u>	<u>CHL</u>	<u>CDOM</u>
P	$a_{\text{SPM},489} \text{ m}^{-1}$ $b_{\text{SPM},652} \text{ m}^{-1}$	$a_{\text{PHY},675} \text{ m}^{-1}$ $b_{\text{PHY},675} \text{ m}^{-1}$	$a_{\text{CDOM},489} \text{ m}^{-1}$
C	$C_{\text{SPM}} \text{ g m}^{-3}$	$C_{\text{CHL}} \text{ mg m}^{-3}$	$a_{\text{CDOM}} / a_{\text{CDOM}}^s$ (Bounded by 0 and 1)
P'	$a'_{\text{SPM}} \text{ m}^2 \text{ g}^{-1}$ = 0.049 $b'_{\text{SPM}} \text{ m}^2 \text{ g}^{-1}$ = 0.417	$a'_{\text{CHL}} \text{ m}^2 \text{ mg}^{-1}$ = 0.013 $b'_{\text{CHL}} \text{ m}^2 \text{ mg}^{-1}$ = 0.125	$a_{\text{CDOM}}^s \text{ m}^{-1}$
F	$\sum_0^3 x_{ai} [\lambda/489]^i$ $x_{a0} = 19.741$ $x_{a1} = -43.174$ $x_{a2} = 32.864$ $x_{a3} = -8.428$ $\sum_0^3 x_{bi} [\lambda/652]^i$ $x_{b0} = 0.508$ $x_{b1} = 3.786$ $x_{b2} = -5.447$ $x_{b3} = 2.153$	$a_{\text{CHL}} / a_{\text{CHL},675}$ $b_{\text{CHL}} / b_{\text{CHL},675}$ Stramski et al., 2002	$\exp^{S_g(489 - \lambda)}$ $S_g = 0.0165 \text{ nm}^{-1}$

